Commands for Autonomous System Last Edited 9/30/2018

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| System | Name | Description |
| Motor Controller (input) | Acceleration (Linear Float) | Speed Applied |
| Motor Controller (Output) | Angular Velocity (Linear Float) | Brushless Shaft Speed Output |
| Brakes (input) | Applied Force (Log Float) | Brakes Applied |
| Brakes (Input) | Brake System (Integer) | Front or Back or both Brakes used |
| Brakes (Output) | Brake Applied (Float) | Feedback for Brake Applied |
| Steering (Input) | Angle (Signed Integer) | Angular Offset of Steering Wheel |
| Steering (Output) | Angle (Signed Integer) | Angular Offset of Steering Wheel |
| Sensors (Input) | Sensor Address (Integer) | Send It |
| Sensors (Output) | Sensor Address (Integer) | Confirmation Response |
| Sensors (Output) | Wanted Value (Float) | Sensor Data |